

### On Banach Common Fixed Point Results in Symmetric $G_d$ -Metric Spaces

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**Abstract.** In this paper, common fixed-point problems for locally contractive mappings in symmetric  $G_d$ -metric like spaces are proved and error bounds are discussed in detail. Besides, we gave examples to validate main results. In our research, we have proved that a pair of self-mappings satisfies Banach contraction, in local domain instead of global domain. Also, application of  $G_d$ -metric like spaces for solving Urysohn integral equations is given.

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**Key Words:** Dislocated generalized metric spaces, symmetric metric spaces, common fixed point, closed ball, locally contractive mappings.

#### 1. INTRODUCTION

Self-mappings  $F_1$  and  $F_2$  on  $S$  are Banach contraction mappings if  $d(F_1t, F_2u) \leq \xi d(t, u)$  satisfies for all  $t, u \in S$  where  $0 \leq \xi < 1$ . As of late, numerous outcomes showed up in writing related to fixed point brings about complete metric spaces supplied with a halfway requesting. Ran and Reurings [13] demonstrated a simple case of Banach's fixed point hypothesis in partial ordered metric space and offered applications to matrix equations. Subsequently, Nieto et. al. [11] expanded the outcomes for non-decreasing functions and applied this outcome to acquire the solution for the first order ordinary differential equation with periodic boundary conditions. In [10], Z. Mustafa and B. Sims introduced an alternative more robust generalization of metric spaces called  $G$ -metric spaces. They did this to overcome fundamental flaws in B. C. Dhage's [7] theory of generalized metric

spaces, flaws that invalidate most of the results claimed for these spaces. During the sixties, 2-metric spaces were introduced by Gähler. A 2-metric is a generalization of the usual notion of a metric, but different authors proved that there is no relation between these two functions. For instance, Ha et al. in show that a 2-metric need not be a continuous function of its variables, whereas an ordinary metric is. Further, there is no easy relationship between results obtained in the two settings, in particular the contraction mapping theorem in metric spaces and in 2-metric spaces are unrelated. These considerations led Bapure Dhage in his PhD thesis to introduce a new class of generalized metrics called  $D$ -metrics. Recently, Arshad [4] demonstrated fixed points of a mapping fulfilling a contractive condition on closed ball  $(C_B)$  in ordered complete partial metric space. The overwhelmed mapping [4] which fulfills the condition  $F_1u \preceq u$  happens normally. For example,  $u$  signifies the aggregate amount of wheat cultivated over a specific period and  $F_1(u)$  gives the amount of wheat used over a similar period in a specific town, at that point we should have  $F_1u \preceq u$ . To access more comprehensive information, readers may refer to the following articles [3, 5, 6, 7, 8, 12, 14, 15, 16] and the associated references provided in them.

This article presents the demonstration of fixed point existence for two self-mappings that operate within a closed ball  $(C_B)$ , a subset of  $S$ , and conform to a Banach type contractive condition. The primary focus of the article is to establish the presence of fixed points within  $C_B$ . A significant feature of the article is the adoption of local contractive conditions as opposed to global contractive conditions. This particular approach is employed to derive fixed point results that are both unique and common. To verify the reliability and soundness of the results, the article includes a range of examples that serve to validate the obtained outcomes.

## 2. PRELIMINARIES

Here are some essential preliminary points to enhance readers' convenience and understanding before delving into the topic.

**Definition 2.1.** [4] *In partial ordered set  $(S, \preceq)$ , elements  $u, v \in S$  are called comparable elements if either  $u \preceq v$  or  $v \preceq u$ .*

**Definition 2.2.** [4] *In partial ordered set  $(S, \preceq)$ , a self-mapping  $F_1$  on  $S$ , is said to be dominated if  $F_1u \preceq u$  for each  $u \in S$ .*

**Definition 2.3.** [9] *In partial ordered set  $(S, \preceq)$ , a self-mapping  $F_1$  on  $S$ , is said to be dominating if  $u \preceq F_1u$  for each  $u \in S$ .*

Shoaib et al. [10] employed the principles of generalized metric spaces and dislocated generalized metric spaces to establish a range of fixed point theorems. The authors begin by providing clear definitions of these fundamental concepts, namely the generalized metric space and the dislocated generalized metric space. These definitions serve to enhance the understanding of these key concepts and lay the foundation for the subsequent theoretical developments presented in the paper.

**Definition 2.4.** [10] *Let  $S \neq \phi$ , and mapping  $G : S \times S \times S \rightarrow [0, \infty)$  satisfying:*

(G1)  $G(t, u, v) = 0$  if  $v = u = t$ ,

(G2)  $G(t, t, u) > 0$ , for all  $t, u \in S$  with  $t \neq u$ ,

- (G3)  $G(u, u, v) \leq G(t, u, v)$ , for all  $u, v, t \in S$  and  $t \neq v$ ,
- (G4)  $G(t, u, v) = G(u, t, v) = G(u, v, t) = G(t, v, u) = G(v, t, u) = G(v, u, t)$ , (symmetry in all three variables),
- (G5)  $G(u, v, t) = G(u, u, w) + G(w, v, t)$ , for all  $w, t, u, v \in S$ , (rectangular inequality), is called a  $G$ -metric (GM) and the pair  $(S, G)$  is called a  $G$ -metric space ( $G_{MS}$ ). The function  $G$  is continuous in three of its variables.

**Definition 2.5.** [10] Let  $S \neq \emptyset$ , and mapping  $G_d: S \times S \times S \rightarrow [0, \infty)$  satisfying;

- (i)  $G_d(u, v, t) = G_d(u, t, v) = G_d(t, u, v) = G_d(t, v, u) = G_d(v, t, u) = G_d(v, u, t) = 0$ , then  $u = v = t$ ,
- (ii)  $G_d(u, v, t) \leq G_d(u, u, w) + G_d(w, v, t)$ , for all  $w, t, u, v \in S$ , (rectangular inequality), is a quasi metric and the pair  $(S, G_d)$  is quasi  $G_d$ -metric space.

From (i), if  $G_d(u, v, t) = G_d(u, t, v) = G_d(t, u, v) = G_d(t, v, u) = G_d(v, t, u) = G_d(v, u, t) = 0$ , then  $t = u = v$ . But  $u = v = t$  does not assure that  $G_d(t, u, v) = 0$ . Along with (i) and (ii) if  $G_d(t, u, v) = G_d(t, v, u) = G_d(u, t, v) = G_d(u, v, t) = G_d(v, t, u) = G_d(v, u, t)$ , for all  $t, u, v \in S$  holds then  $(S, G_d)$  becomes  $G_{MLS}$ .

**Example 2.6.** For a set  $S = R$  and mapping  $G_d: S \times S \times S \rightarrow [0, \infty)$  defined by

$$G_d(u, v, t) = d(u, v) + d(v, t) + d(u, t), \text{ for all } u, v, t \in S$$

where  $d: S \times S \rightarrow [0, \infty)$  is usual metric. Then clearly  $(S, G_d)$  is a generalized metric Like Space.

**Definition 2.7.** [1]  $G_{MLS}(S, G_d)$  is said to be complete if every Cauchy sequence in  $(S, G_d)$  is convergent in  $S$ .

**Definition 2.8.** [1] In  $G_{MLS}(S, G_d)$ , for  $t_0 \in S$ ,  $0 < \mathfrak{J}$ , closed ball ( $C_B$ ) with center  $t_0$  and radius  $\mathfrak{J}$  is

$$C_B = \overline{B_{G_d}(t_0, \mathfrak{J})} = \{t \in S : G_d(t_0, t, t) \leq \mathfrak{J}\}$$

**Lemma 2.9.** [9] Let  $(S, G_d)$  be a  $G_{MLS}$  then for all  $t, u, v \in S$

$$G_d(t, t, u) \leq 2G_d(t, u, v)$$

**Definition 2.10.** [2] Let  $F_1$  and  $F_2$  be self-mappings on  $S$ . If  $u = F_1v = F_2v$  for some  $v \in S$ , then  $v \in S$  is said to be a coincidence point for mappings  $F_1$  and  $F_2$  whereas  $v \in S$  is called point of coincidence of mappings  $F_1$  and  $F_2$ .

Note that, if  $u = v$  then  $u \in S$  becomes common fixed point of self-mappings  $F_1$  and  $F_2$ .

**Proposition 2.11.** [1] Let  $(S, G_d)$  be a  $G_{MLS}$ . Then the function  $G_d(t, u, v)$  is continuous for three variables.

**Proposition 2.12.** [1] In  $G_{MLS}(S, G_d)$ , following conditions are equivalent:

- (i)  $\{t_n\}$  is Cauchy sequence,
- (ii) for  $\varepsilon > 0$ , there exists  $n_0 \in \mathbb{N}$ , such that  $G_d(t_m, t_n, t_n) < \varepsilon$ , for all  $n, m \geq n_0$ .

**Definition 2.13.** [1] Let  $(S, G_d)$  be  $G_{MLS}$  and  $\{t_n\}$  be a sequence in  $S$ . A point  $t \in S$  is called a limit point of  $\{t_n\}$  if  $\lim_{n \rightarrow +\infty} G_d(t, t_n, t_n) = 0$ . Also, one can say  $\{t_n\}$  converges to  $t$ . Therefore, if  $t_n \rightarrow t$ , then for any  $\varepsilon > 0$ , there exists  $n_0 \in \mathbb{N}$ , such that  $G_d(t, t_n, t_n) < \varepsilon$ , for all  $n \geq n_0$ .

**Definition 2.14.** [6] Let  $(S, G_d)$  be a compact  $G_{MLS}$ , if and only if every sequence in  $S$  has convergent subsequence in  $S$ .

**Definition 2.15.** [10] Let  $(S, G_d)$  be a  $G_{MLS}$  then  $G_d$  is symmetric in two variables if for all  $t, u \in S$

$$G_d(t, u, u) = G_d(u, t, t).$$

### 3. MAIN RESULTS

In this particular section, the article focuses on proving common fixed point results for self-mappings within the closed ball ( $C_B$ ) rather than the entire space  $S$ . The context of the investigation is set within the framework of generalized metric-like spaces ( $G_{MLS}$ ). Notably, the article also includes an example to validate the main result, which demonstrates that the contractive condition holds within  $C_B$  but fails within the broader space  $S$ . Specifically, it highlights the possibility that while the contractive condition may fail within the full space  $S$ , it can still be satisfied within subsets of  $S$ , such as the  $C_B$ . This example serves as concrete evidence to support the findings and reinforces the importance of considering the  $C_B$  when analyzing fixed point properties.

**Theorem 3.1.** Suppose  $(S, G_d)$  be a symmetric and complete  $G_{MLS}$  and  $F_1, F_2 : S \rightarrow S$  be any two dominated mappings. Suppose that,

$$G_d(F_1t, F_2u, F_2v) \leq \xi G_d(t, u, v), \quad (3.1)$$

for all  $t, u, v \in C_B \subseteq S$  and for some  $\xi \in [0, 1)$ . Also,

$$G_d(t_0, t_1, t_1) = G_d(t_0, F_2t_0, F_2t_0) \leq (1 - \xi)\mathfrak{J}. \quad (3.2)$$

Then there exist unique  $t_0 \in C_B$  such that  $F_1t_0 = F_2t_0 = t_0$ .

*Proof.* Let  $t_0 \in C_B$  and consider the sequence  $\{t_n\}_{n \in \mathbb{N}}$  such that  $t_{2n+1} = F_2t_{2n}$  and  $t_{2n+2} = F_1t_{2n+1}$ , where  $F_1$  and  $F_2$  are dominated mappings then  $t_n \leq t_{n-1}$ , for all  $n = 0, 1, 2, \dots$ . If  $t_{2n+1} = F_1t_{2n+1} = F_2t_{2n}$  then  $t_{2n+1} \in C_B$  is fixed point of  $F_1$  and  $F_2$ . But if  $F_1t_{2n+1} \neq F_2t_{2n}$  then consider

$$\begin{aligned} G_d(t_0, t_1, t_1) &= G_d(t_0, F_2t_0, F_2t_0) \leq (1 - \xi)\mathfrak{J}, \\ G_d(t_0, t_1, t_1) &\leq \mathfrak{J}. \end{aligned}$$

Clearly  $t_1 \in C_B$ . Agnain, consider the relation

$$\begin{aligned} G_d(t_1, t_2, t_2) &= G_d(F_2t_0, F_1t_1, F_1t_1) = G_d(F_1t_1, F_2t_0, F_2t_0), \\ &\leq \xi G_d(t_0, t_1, t_1). \end{aligned}$$

Now for  $t_2 \in S$ , using triangular property,

$$\begin{aligned} G_d(t_0, t_2, t_2) &\leq G_d(t_0, t_1, t_1) + G_d(t_1, t_2, t_2), \\ &\leq (1 + \xi)G_d(t_0, t_1, t_1), \\ &\leq (1 + \xi)(1 - \xi)\mathfrak{J}, \\ &\leq (1 - \xi^2)\mathfrak{J}, \\ &\leq \mathfrak{J}. \end{aligned}$$

Therefore,  $t_2 \in C_B$ . Again, consider the relation

$$\begin{aligned} G_d(t_2, t_3, t_3) &= G_d(F_1 t_1, F_2 t_2, F_2 t_2), \\ &\leq \xi G_d(t_1, t_2, t_2), \\ &\leq \xi^2 G_d(t_0, t_1, t_1). \end{aligned}$$

For  $t_3 \in S$

$$\begin{aligned} G_d(t_0, t_3, t_3) &\leq G_d(t_0, t_1, t_1) + G_d(t_1, t_2, t_2) + G_d(t_2, t_3, t_3), \\ &\leq G_d(t_0, t_1, t_1) + \xi G_d(t_0, t_1, t_1) + \xi^2 G_d(t_0, t_1, t_1), \\ &= (1 + \xi + \xi^2) G_d(t_0, t_1, t_1), \\ &\leq (1 + \xi + \xi^2)(1 - \xi) \mathfrak{J}, \quad \because \text{(using (3.1))} \\ &= (1 - \xi^3) \mathfrak{J}, \\ &\leq \mathfrak{J}. \end{aligned}$$

Therefore,  $t_3 \in C_B$ . Now let  $t_4, t_5, t_6, \dots, t_i \in C_B$ , using mathematical induction for all  $i = 0, 2, 4, 6, \dots$  gives,

$$\begin{aligned} G_d(t_i, t_{i+1}, t_{i+1}) &= G_d(F_1 t_{i-1}, F_2 t_i, F_2 t_i), \\ &\leq \xi G_d(t_{i-1}, t_i, t_i) = \xi G_d(F_2 t_{i-2}, F_1 t_{i-1}, F_1 t_{i-1}) \\ &= \xi G_d(F_1 t_{i-1}, F_2 t_{i-2}, F_2 t_{i-2}), \\ &\leq \xi^2 G_d(t_{i-1}, t_{i-2}, t_{i-2}), \\ &\vdots \\ &\leq \xi^i G_d(t_0, t_1, t_1). \end{aligned}$$

Now by rectangular property for  $t_i \in S$ ,

$$\begin{aligned} G_d(t_0, t_i, t_i) &\leq G_d(t_0, t_1, t_1) + G_d(t_1, t_2, t_2) + \dots + G_d(t_{i-1}, t_i, t_i), \\ &\leq G_d(t_0, t_1, t_1) + \xi G_d(t_0, t_1, t_1) + \dots + \xi^{i-1} G_d(t_0, t_1, t_1), \\ &= (1 + \xi + \xi^2 + \dots + \xi^{i-1}) G_d(t_0, t_1, t_1), \\ &\leq (1 - \xi^i) \mathfrak{J}, \\ &\leq \mathfrak{J}. \end{aligned}$$

Clearly  $t_i \in C_B$ , for all  $i \in \mathbb{N}$ . Hence, the sequence  $\{t_n\}_{n \in \mathbb{N}} \subseteq C_B$ . For sequence  $\{t_n\}_{n \in \mathbb{N}}$  to be Cauchy sequence, for  $m, n \in \mathbb{N}$  with  $n < m$ , consider

$$\begin{aligned} G_d(t_n, t_m, t_m) &\leq G_d(t_n, t_{n+1}, t_{n+1}) + G_d(t_{n+1}, t_{n+2}, t_{n+2}) + \dots + G_d(t_{m-1}, t_m, t_m), \\ &\leq \xi^n (1 + \xi + \xi^2 + \dots + \xi^{m-n-1}) G_d(t_0, t_1, t_1), \\ &= \xi^n \left( \frac{1 - \xi^{m-n}}{1 - \xi} \right) G_d(t_0, t_1, t_1), \tag{3.3} \\ &\leq \frac{\xi^n}{1 - \xi} G_d(t_0, t_1, t_1), \\ &\leq \frac{\xi^n}{1 - \xi} (1 - \xi) \mathfrak{J}, \\ &\leq \xi^n \mathfrak{J}. \end{aligned}$$

As  $\xi \in [0, 1)$ , then  $\xi^n \rightarrow 0$  if  $n \rightarrow +\infty$ . Therefore, for every  $\varepsilon \in \mathbb{R}^+$ , there exists  $j \in \mathbb{R}$  such that,

$$G_d(t_n, t_m, t_m) \leq \xi^n \mathbb{1} = \varepsilon, \text{ for } m > n \geq j.$$

Hence  $\{t_n\}_{n \in \mathbb{N}}$  is Cauchy sequence in  $C_B$ . As  $S$  is complete then there exists  $t_0 \in S$  such that  $t_n \rightarrow t_0$  for  $n \rightarrow +\infty$  and hence

$$\lim_{n \rightarrow +\infty} G_d(t_0, t_n, t_n) = 0.$$

To check  $t_0 \in C_B$  is either common fixed point of  $F_1, F_2 : S \rightarrow S$  or not consider

$$G_d(t_0, F_1 t_0, F_1 t_0) \leq G_d(t_0, t_{2n+1}, t_{2n+1}) + G_d(t_{2n+1}, F_1 t_0, F_1 t_0).$$

By using Definition 2.15 and Proposition 2.11, gives

$$\begin{aligned} G_d(t_0, F_1 t_0, F_1 t_0) &\leq G_d(t_0, t_{2n+1}, t_{2n+1}) + G_d(F_1 t_0, F_2 t_{2n}, F_2 t_{2n}), \\ &\leq G_d(t_0, t_{2n+1}, t_{2n+1}) + \zeta G_d(t_0, t_{2n}, t_{2n}), \\ G_d(t_0, F_1 t_0, F_1 t_0) &\rightarrow 0, \text{ when } n \rightarrow +\infty. \\ F_1 t_0 &= t_0. \end{aligned}$$

Again consider

$$\begin{aligned} G_d(t_0, F_2 t_0, F_2 t_0) &\leq G_d(t_0, t_{2n+2}, t_{2n+2}) + G_d(t_{2n+2}, F_2 t_0, F_2 t_0), \\ &\leq G_d(t_0, t_{2n+2}, t_{2n+2}) + \xi G_d(t_{2n+1}, t_0, t_0), \end{aligned}$$

By using Definition 2.15 and Proposition 2.11, gives

$$G_d(t_0, F_2 t_0, F_2 t_0) \leq 0, \text{ when } n \rightarrow +\infty.$$

As  $G_d(t_0, F_2 t_0, F_2 t_0) \not\leq 0$ , so

$$\begin{aligned} G_d(t_0, F_2 t_0, F_2 t_0) &= 0, \\ F_2 t_0 &= t_0. \end{aligned}$$

Hence  $t_0 \in C_B$  is fixed point for mappings  $F_1$  and  $F_2$ , i.e.  $F_1 t_0 = F_2 t_0 = t_0$ . for uniqueness of fixed point, consider  $\{u_0, v_0\} \subseteq C_B$  such that  $F_1(u_0) = F_2(u_0) = u_0$  and  $F_1(v_0) = F_2(v_0) = v_0$ . Now consider by relation,

$$\begin{aligned} G_d(F_1 u_0, F_2 v_0, F_2 v_0) &\leq \xi G_d(u_0, v_0, v_0), \\ G_d(u_0, v_0, v_0) &\leq \xi G_d(u_0, v_0, v_0), \\ (1 - \xi)G_d(u_0, v_0, v_0) &\leq 0. \end{aligned}$$

As  $1 - \xi > 0$ , then

$$\begin{aligned} G_d(u_0, v_0, v_0) &= 0, \\ u_0 &= v_0. \end{aligned}$$

It is not true ( $\because u_0 \neq v_0$ ). Therefore, common fixed point of  $F_1$  and  $F_2$ , is unique.  $\square$

**Remark 3.2.** Theorem 3.1, also holds for dominating mappings  $F_1$  and  $F_2$ .

**Example 3.3.** Let  $S = [0, \infty)$  and  $G_d : S \times S \times S \rightarrow [0, \infty)$  be a mapping defined by,

$$G_d(t, u, v) = \max \{|t|, |u|, |v|\}$$

for all  $t, u, v \in S$ , with order say  $t \geq u \geq v$  then  $(S, G_d)$  is symmetric and complete  $G_{MLS}$ . Closed ball with  $\mathfrak{J} = 1$  and  $t_0 = \frac{1}{2}$  is  $C_B = [0, 1]$ . Let  $F_1, F_2 : S \rightarrow S$  are mappings defined by,

$$F_1 t = \begin{cases} \frac{w}{3} & \text{if } 0 \leq w \leq 1 \\ w + \frac{1}{2} & \text{if } 1 < w < \infty \end{cases},$$

$$F_2 t = \begin{cases} \frac{w}{5} & \text{if } 0 \leq w \leq 1 \\ w + \frac{1}{3} & \text{if } 1 < w < \infty \end{cases}.$$

Clearly  $F_1$  and  $F_2$  are, dominated mappings inside of  $C_B$ , but not dominated outside of  $C_B$ . Also for  $\xi = \frac{1}{2} \in (0, 1)$  such that,

$$(1 - \xi)\mathfrak{J} = \left(1 - \frac{1}{2}\right) \cdot 1 = \frac{1}{2}$$

Also,

$$G_d(t_0, t_1, t_1) = \max\{|t_0|, |t_1|, |t_2|\} = \max\{|t_0|, |F_2 t_0|, |F_2 t_0|\}$$

As  $F_2$  being dominated mapping  $F_2 t_0 \leq t_0 \Rightarrow |t_1| \leq |t_0|$

$$G_d(t_0, t_1, t_1) = |t_0| = \frac{1}{2},$$

$$G_d(t_0, t_1, t_1) = (1 - \xi)\mathfrak{J}.$$

Also for all  $t, u, v \in [0, 1]$

$$G_d(F_1 t, F_2 u, F_2 v) = G_d\left(\frac{t}{3}, \frac{u}{5}, \frac{v}{5}\right) = \max\left\{\left|\frac{t}{3}\right|, \left|\frac{u}{5}\right|, \left|\frac{v}{5}\right|\right\}.$$

As  $\frac{t}{3} \geq \frac{t}{5} \geq \frac{u}{5} \geq \frac{v}{5}$ , then

$$G_d(F_1 t, F_2 u, F_2 v) = \left|\frac{t}{3}\right| = \frac{|t|}{3},$$

and

$$\xi G_d(t, u, v) = \frac{1}{2} \max\{|t|, |u|, |v|\} = \frac{|t|}{2},$$

$$G_d(F_1 t, F_2 u, F_2 v) < \xi G_d(t, u, v).$$

Hence contractive condition is satisfied in  $C_B$ . For  $t, u, v \in (1, \infty)$ ,

$$G_d(F_1 t, F_2 u, F_2 v) = \max\left\{\left|t + \frac{1}{2}\right|, \left|u + \frac{1}{3}\right|, \left|v + \frac{1}{3}\right|\right\}$$

As  $t + \frac{1}{2} \geq t + \frac{1}{3} \geq u + \frac{1}{3} \geq v + \frac{1}{3}$ , then

$$G_d(F_1t, F_2u, F_2v) = \left| t + \frac{1}{2} \right|,$$

and

$$\begin{aligned} \xi G_d(t, u, v) &= \frac{1}{2} \max\{|t|, |u|, |v|\} = \frac{|t|}{2}, \\ G_d(F_1t, F_2u, F_2v) &\geq \xi G_d(t, u, v). \end{aligned}$$

Clearly, outside of the  $C_B$  contractive condition is failed. This shows that all conditions of Theorem 3.1, for mappings  $F_1$  and  $F_2$  are satisfied inside of  $C_B$ . Moreover, there exists  $0 \in [0, 1]$  such that  $F_10 = F_20 = 0$ .

Note that, Theorem 3.1, can also be proved for single mapping as shown in following corollary.

**Corollary 3.4.** Suppose  $(S, G_d)$  be a symmetric and compact  $G_{MLS}$  and  $F_1 : S \rightarrow S$  be any dominated mapping and  $t_0, t, u, v \in S, \mathfrak{J} > 0$ . Suppose that, there exist  $\xi \in [0, 1)$  such that,

$$G_d(F_1t, F_1v, F_1v) \leq \xi G_d(t, u, v)$$

for all  $t, u, v \in C_B \subseteq S$ , and

$$G_d(t_0, t_1, t_1) = G_d(t_0, F_1t_0, F_1t_0) \leq (1 - \xi)\mathfrak{J}.$$

Then there exist unique  $t_0 \in C_B$  such that  $F_1t_0 = t_0$ .

*Proof.*  $(S, G_d)$  being compact metric space is complete and totally bounded. Then follow the proof of Theorem 3.1.  $\square$

**Corollary 3.5.** Suppose  $(S, G_d)$  be a symmetric and complete  $G_{MLS}$  and  $F_1 : S \rightarrow S$  be two dominated mapping and  $t_0, t, u, v \in S, \mathfrak{J} > 0$ . Suppose that there exists  $\xi \in [0, 1)$  such that,

$$G_d(F_1t, F_1v, F_1v) \leq \xi G_d(t, u, v)$$

for all  $t, u, v \in C_B \subseteq S$ , and

$$G_d(t_0, t_1, t_1) = G_d(t_0, F_1t_0, F_1t_0) \leq (1 - \xi)\mathfrak{J}$$

Then there exist unique  $t_0 \in C_B$  such that  $F_1t_0 = t_0$ .

*Proof.* In Theorem 3.1 using  $F_1 = F_2$  to obtain unique fixed point for single mapping  $t_0 = F_1t_0$ .  $\square$

Proof of the following corollary for noncomparable elements, is same as the proof of Theorem 3.1.

**Corollary 3.6.** Suppose  $(S, G_d)$  be a symmetric and complete  $G_{MLS}$  and  $F_1, F_2 : S \rightarrow S$  are any two dominated mappings and  $t_0, t, u, v \in S, \mathfrak{J} > 0$ . Suppose that there exists  $\xi \in [0, 1)$  such that,

$$G_d(F_1t, F_2u, F_2v) \leq \xi G_d(t, u, v),$$

for all  $t, u, v \in C_B$ , and

$$G_d(t_0, t_1, t_1) \leq (1 - \xi)\mathfrak{J}.$$

Then there exist unique  $t_0 \in C_B$  such that  $F_1 t_0 = F_2 t_0 = t_0$ .

*Proof.* Consequence of Theorem 3.1. □

**Corollary 3.7.** From Theorem 3.1, iterative sequence  $\{t_n\}$ , with arbitrary  $t_0 \in C_B \subseteq S$ , converges to unique common fixed-point  $t_0 \in C_B$  of dominated mappings  $F_1$  and  $F_2$ . Error estimates are the prior estimate

$$G_d(t_n, t_0, t_0) \leq \frac{\xi^n}{1-\xi} G_d(t_0, t_1, t_1) \tag{3.4}$$

and the posterior estimate

$$G_d(t_n, t_0, t_0) \leq \frac{\xi}{1-\xi} G_d(t_{n-1}, t_n, t_n) \tag{3.5}$$

*Proof.* From (3.3),

$$G_d(t_n, t_m, t_m) \leq \xi^n \left( \frac{1-\xi^{m-n}}{1-\xi} \right) G_d(t_0, t_1, t_1)$$

As the sequence  $\{t_n\}$  is convergent to  $t_0 \in C_B$ , then  $t_m \rightarrow t_0$  as  $m \rightarrow \infty$  and  $1-\xi^{m-n} \rightarrow 1$ . Therefore, above relation leads to the prior estimate, i.e.,

$$G_d(t_n, t_0, t_0) \leq \frac{\xi^n}{1-\xi} G_d(t_0, t_1, t_1)$$

Setting  $n = 1$  and write  $u_0$  for  $t_0$  and  $u_1$  for  $t_1$  in above relation to get

$$G_d(u_1, t_0, t_0) \leq \frac{\xi}{1-\xi} G_d(u_0, u_1, u_1)$$

Letting  $u_0 = t_{n-1}$  then  $u_1 = F_2 u_0 = F_2 t_{n-1} = t_n$  in above relation gives the posterior estimate (3.3),

$$G_d(t_n, t_0, t_0) \leq \frac{\xi}{1-\xi} G_d(t_{n-1}, t_n, t_n)$$

Note that, the prior error bound (3.4) can be used in the beginning of calculation for assessing the necessary number of steps to get required accuracy. While posterior error bound (3.5) can be used at middle of the road stages or at the end of calculation. Posterior error bound at any rate as exact as prior error bound. □

**Example 3.8.** Let  $S = [0, \infty)$  and  $G_d : S \times S \times S \rightarrow [0, \infty)$  be a mapping defined by,

$$G_d(t, u, v) = \max \{|t|, |u|, |v|\}$$

for all  $t, u, v \in S$  with order say  $t \geq u \geq v$  then  $(S, G_d)$  is symmetric and complete  $G_{MLS}$ . Closed ball with  $\mathfrak{J} = 1$  and  $t_0 = \frac{1}{2}$  is  $C_B = [0, 1] \subset S$ . Let  $F_1, F_2 : S \rightarrow S$  are mappings defined by,

$$F_2 t = \begin{cases} \frac{t}{5} & \text{if } 0 \leq t \leq 1 \\ t + \frac{1}{3} & \text{if } 1 < t < \infty \end{cases},$$

$$F_1 t = \begin{cases} \frac{t}{3} & \text{if } 0 \leq t \leq 1 \\ t + \frac{1}{2} & \text{if } 1 < t < \infty \end{cases}.$$

Obviously,  $F_1$  and  $F_2$  are, dominated mappings inside of  $C_B$  but not dominated outside of  $C_B$ . Also let  $\xi = \frac{1}{2} \in [0, 1)$ . Construct the iterative sequence with initial guess  $t_0 = \frac{1}{2} \in [0, 1]$  as

$$\begin{array}{ccc} n & t_{2n+1} = F_2 t_{2n} & t_{2n+2} = F_1 t_{2n+1} \\ 0 & \frac{3}{2(\sqrt{15})^1} & \frac{1}{2(\sqrt{15})^1} \\ 1 & \frac{3}{2(\sqrt{15})^2} & \frac{1}{2(\sqrt{15})^2} \\ 2 & \frac{3}{2(\sqrt{15})^3} & \frac{1}{2(\sqrt{15})^3} \\ \vdots & \vdots & \vdots \\ m & \frac{3}{2(\sqrt{15})^m} & \frac{1}{2(\sqrt{15})^m} \end{array}$$

Let  $2m - 1 = \varphi$ , then for every odd  $\varphi \in \mathbb{N}$  gives,

$$t_\varphi = \frac{3}{2(\sqrt{15})^{\varphi+1}}, t_{\varphi+1} = \frac{1}{2(\sqrt{15})^{\varphi+1}} \quad (3.6)$$

Now as,

$$G_d(t_0, t_1, t_1) = \max\{|t_0|, |t_1|\} = t_0 = \frac{1}{2}.$$

Also, as

$$G_d(t_\varphi, t, t) = \max\{|t_\varphi|, |t|\}.$$

As from (3.6), sequence  $\{t_\varphi\} \in C_B$  is decreasing and bounded below. Then there exist greatest lower bound  $t_0 \in [0, 1]$  such that  $t_\varphi \geq t_0$  for all  $\varphi \in \mathbb{N}$  and hence,

$$G_d(t_\varphi, t_0, t_0) = t_\varphi.$$

Now from Corollary 3.7 (3.4),

$$\begin{aligned} G_d(t_\varphi, t_0, t_0) &\leq \frac{\xi^\varphi}{1-\xi} G_d(t_0, t_1, t_1), \\ t_\varphi &\leq \frac{\left(\frac{1}{2}\right)^\varphi}{1-\frac{1}{2}} \cdot \frac{1}{2}, \\ \frac{3}{2(\sqrt{15})^{\varphi+1}} &\leq \frac{1}{2^\varphi}, \\ \frac{3}{2\sqrt{15}} &\leq \frac{(\sqrt{15})^\varphi}{2^\varphi}, \\ \frac{\ln \frac{3}{2\sqrt{15}}}{\ln \frac{\sqrt{15}}{2}} &\leq \varphi, \\ -1.4353 &\leq \varphi. \end{aligned}$$

For every odd integer  $\wp \geq 1$ , sequence  $\{t_\wp\}$ , becomes convergent, i.e., for every odd  $\wp \in \mathbb{N}$  relation (3. 6) becomes,

$\wp$	$t_\wp$	$t_{\wp+1}$
1	0.10000000000	0.03333333333
3	0.00666666667	0.00222222222
5	0.00044444444	0.00014814815
7	0.00002962296	0.00000987654
$\vdots$	$\vdots$	$\vdots$

Hence, from above table, when odd  $\wp \in \mathbb{N}$  increases then  $t_\wp \rightarrow t_0$  and  $t_0 \in [0, 1]$  becomes common fixed point of mapping  $F_1$  and  $F_2$ . Clearly, from the iterative sequence  $t_0 = 0 \in [0, 1]$ , such that  $F_1 0 = F_2 0 = 0$ .

#### 4. APPLICATION TO NONLINEAR SYSTEM OF INTEGRAL EQUATIONS

In this section, the nonlinear integral equation is resolved by employing Theorem 3.1. To accomplish this, the interval  $S = ([t_1, t_2], \mathbb{R}^n)$ , where  $C_B = [t_1, t_2]$  and  $b > 0$ . By utilizing Theorem 3.1, a suitable solution for the nonlinear integral equation within the specified interval  $S$  can be obtained by using

$$G_d(u, v, v) = 2 \sup_{\tau \in [t_1, t_2]} |u(\tau) - v(\tau)| \sqrt{1 + b^2 e^{i \tan^{-1} b}} \tag{4. 7}$$

for all  $u, v \in S$ , then  $(S, G_d)$  is complete  $G_{MLS}$ . The following result establishes an existence theorem for a common solution to a system of two nonlinear Urysohn integral equations.

**Theorem 4.1.** *Let's consider the Urysohn integral equations given by*

$$\begin{cases} u(t) = \int_{t_1}^{t_2} L_1(t, s, u(s)) ds + g_1(t), \\ u(t) = \int_{t_1}^{t_2} L_2(t, s, u(s)) ds + g_2(t), \end{cases} \tag{4. 8}$$

where  $t \in C_B$ , and  $u, g_1, g_2 \in S$ . The functions  $L_1, L_2 \in [t_1, t_2] \times [t_1, t_2] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ . Suppose that for each  $u, v \in S$ ,  $M_u, N_u \in S$ , defined as

$$M_u(t) = \int_{t_1}^{t_2} L_1(t, s, u(s)) ds, \quad \text{and} \quad N_u(t) = \int_{t_1}^{t_2} L_2(t, s, u(s)) ds,$$

for all  $t \in [t_1, t_2]$ . If there exists  $\mathcal{L} \in [0, 1)$  such that for every  $u, v \in S$  for all  $t \in [t_1, t_2]$ . If there exists a value  $\mathcal{L} \in [0, 1)$  such that for every  $u, v \in S$ , the following inequality holds

$$|M_u(t) - N_v(t) + g_1(t) - g_2(t)| \sqrt{1 + b^2 e^{i \tan^{-1} b}} \leq \mathcal{L} G_d(u, v, v), \tag{4. 9}$$

then the system of integral equations (4. 8) has a unique common solution in  $S$ .

*Proof.* Define  $F_1, F_2 \in S$

$$F_1 u = M_u + g_1, \quad F_2 u = N_u + g_2. \tag{4. 10}$$

Then, from (4. 7 )

$$\begin{aligned} G_d(F_1u, F_2v, F_2v) &= \sup_{t \in [t_1, t_2]} |F_1u(t) - F_2v(t)|, \\ &= \sup_{t \in [t_1, t_2]} |M_u(t) - N_v(t) + g_1(t) - g_2(t)| \sqrt{1 + b^2} e^{i \tan^{-1} b}, \\ &\leq \mathcal{L}G_d(u, v, v), \text{ by } (x), \end{aligned}$$

for every  $u, v \in S$ . By Theorem 3.1, self-mapping  $F_1, F_2 \in S$  have unique common fixed point in  $S$ , which is the unique solution of nonlinear system of Urysohn integral equations (4. 8 ).  $\square$

## 5. CONCLUSION

The opening section of this article provides a brief introduction, while the subsequent section focuses on laying the groundwork and providing necessary background information to aid readers in comprehending the topic. The third section of the article is dedicated to presenting the main results, specifically addressing the existence of a common fixed point for two locally contractive mappings within  $G_{MLS}$ . The validity of Theorem 3.1 is supported by an accompanying example. Additionally, within this section, Corollary 3.6 is discussed, which covers both prior and posterior error estimates. Furthermore, Corollary 3.6 is employed to approximate the common fixed point of the locally contractive mappings in  $G_{MLS}$ . In the final section, the article examines the existence of a common solution to a system of two nonlinear Urysohn integral equations.

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